

Глава IV. Методы исследования математических моделей

4. Асимптотические методы

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Пример

$$\begin{cases} \ddot{y} - \varepsilon(1 - y^2)\dot{y} + y = 0 & (6) \\ y(0) = y_0, \quad \dot{y}(0) = 0 & (7) \end{cases}$$

$$\begin{cases} \dot{y} = u, \\ \dot{u} = \varepsilon(1 - y^2)u - y, \\ y(0) = y_0, \quad u(0) = 0 \end{cases} \quad (28)$$

$$\begin{cases} y = a \cdot \cos(t + \theta), \\ u = -a \cdot \sin(t + \theta), \\ a = a(t); \quad \theta = \theta(t). \end{cases} \quad (29)$$

$$\begin{aligned} (28), (29) \Rightarrow \dot{a} \cdot \cos(t + \theta) - a \cdot \sin(t + \theta)(1 + \dot{\theta}) &= -a \cdot \sin(t + \theta), \\ -\dot{a} \cdot \sin(t + \theta) - a \cdot \cos(t + \theta)(1 + \dot{\theta}) &= -\varepsilon(1 - a^2 \cos^2(t + \theta))a \cdot \sin(t + \theta) - a \cdot \cos(t + \theta) \\ \dot{a} \cdot \cos(t + \theta) &= a \cdot \sin(t + \theta)\dot{\theta}, \end{aligned}$$

$$\dot{a} \cdot \sin(t + \theta) = -a \cdot \cos(t + \theta)\dot{\theta} + \varepsilon(a \cdot \sin(t + \theta) - a^3 \sin(t + \theta) \cos^2(t + \theta)),$$

$$\dot{a} = \varepsilon(a \cdot \sin^2(t + \theta) - a^3 \sin^2(t + \theta) \cos^2(t + \theta)) =$$

$$= \varepsilon \left(a \frac{1 - \cos 2(t + \theta)}{2} - \frac{a^3}{4} \sin^2 2(t + \theta) \right) =$$

$$= \varepsilon \left(\frac{a}{2} - \frac{a}{2} \cos 2(t + \theta) - \frac{a^3}{4} \frac{1 - \cos 4(t + \theta)}{2} \right) =$$

$$= \varepsilon \left(\frac{a}{2} - \frac{a}{2} \cos 2(t + \theta) - \frac{a^3}{8} + \frac{a^3}{8} \cos 4(t + \theta) \right) =$$

$$= \varepsilon \left(\frac{a}{2} \left(1 - \frac{a^2}{4} \right) - \frac{a}{2} \cos 2(t + \theta) + \frac{a^3}{8} \cos 4(t + \theta) \right);$$

$$\dot{\theta} = \frac{\dot{a} \cdot \cos(t + \theta)}{a \cdot \sin(t + \theta)} =$$

$$= \frac{\varepsilon (a \cdot \sin^2(t + \theta) - a^3 \sin^2(t + \theta) \cos^2(t + \theta)) \cos(t + \theta)}{a \cdot \sin(t + \theta)} =$$

$$= \varepsilon \left(\frac{1}{2} \sin 2(t + \theta) - \frac{a^2}{2} \sin 2(t + \theta) \cdot \frac{1 + \cos 2(t + \theta)}{2} \right) =$$

$$= \varepsilon \left(\frac{1}{2} \sin 2(t + \theta) - \frac{a^2}{4} \sin 2(t + \theta) - \frac{a^2}{8} \sin 4(t + \theta) \right).$$

$$\left\{ \begin{array}{l} \dot{a} = \varepsilon \left\{ \frac{a}{2} \left(1 - \frac{a^2}{4} \right) - \frac{a}{2} \cos 2(t + \theta) + \frac{a^3}{8} \cos 4(t + \theta) \right\}, \\ \dot{\theta} = \varepsilon \left\{ \frac{1}{2} \left(1 - \frac{a^2}{2} \right) \sin 2(t + \theta) - \frac{a^2}{8} \sin 4(t + \theta) \right\}, \\ a(0) = y_0, \\ \theta(0) = 0. \end{array} \right.$$

$$x = (a, \theta)^T; \quad X(x, t) = X_1(x, t) \quad \Rightarrow \quad (30) \Leftrightarrow (9)$$

$$\dot{x} = \varepsilon \cdot X(x, t)$$

$$\xi = (\bar{a}, \bar{\theta})^T$$

Первое приближение: $\underline{\dot{\xi}} = \varepsilon A_1(\xi)$

$$A_1(\varepsilon) = \bar{X}_1(\varepsilon) = \left(\frac{\bar{a}}{2} \left(1 - \frac{\bar{a}^2}{4} \right), 0 \right)^T;$$

$$\dot{\xi} = \varepsilon A_1(\xi) \Rightarrow (\dot{\bar{a}}, \dot{\bar{\theta}})^T = \varepsilon \left(\frac{\bar{a}}{2} \left(1 - \frac{\bar{a}^2}{4} \right), 0 \right)^T \Rightarrow$$

$$\left\{ \begin{array}{l} \dot{\bar{a}} = \varepsilon \frac{\bar{a}}{2} \left(1 - \frac{\bar{a}^2}{4} \right), \\ \bar{a}(0) = y_0, \\ \dot{\bar{\theta}} = 0, \\ \bar{\theta}(0) = 0. \end{array} \right. \quad \begin{array}{l} (31) \\ (32) \end{array}$$

$$\bar{a} = \frac{2y_0}{\sqrt{y_0^2 + (4 - y_0^2)e^{-\varepsilon t}}}, \quad \bar{\theta} = 0.$$

$$\underline{x_1 = \xi} \Rightarrow a = \bar{a}; \quad \theta = \bar{\theta} \Rightarrow$$

$$y = \frac{2y_0}{\sqrt{y_0^2 + (4 - y_0^2)e^{-\varepsilon t}}} \cos t$$

$$t \rightarrow \infty \Rightarrow y \rightarrow 2 \cos t$$

$$(21) \Rightarrow \frac{\partial u_1}{\partial t} = X_1(\xi, t) - \bar{X}_1(\xi) \Rightarrow$$

$$(30) \Rightarrow$$

$$X_1(\xi, t) = \begin{pmatrix} \frac{\bar{a}}{2} \left(1 - \frac{\bar{a}^2}{4}\right) - \frac{\bar{a}}{2} \cos 2(t + \bar{\theta}) + \frac{\bar{a}^3}{8} \cos 4(t + \bar{\theta}) \\ \frac{1}{2} \left(1 - \frac{\bar{a}^2}{2}\right) \sin 2(t + \bar{\theta}) - \frac{\bar{a}^2}{8} \sin 4(t + \bar{\theta}) \end{pmatrix}$$

$$A_1(\xi) = \bar{X}_1(\xi) = \begin{pmatrix} \frac{\bar{a}^2}{2} \left(1 - \frac{\bar{a}^2}{4}\right) \\ 0 \end{pmatrix} \Rightarrow$$

$$\frac{\partial u_1}{\partial t} = \begin{pmatrix} -\frac{\bar{a}^2}{2} \cos 2(t + \bar{\theta}) + \frac{\bar{a}^3}{8} \cos 4(t + \bar{\theta}) \\ \frac{1}{2} \left(1 - \frac{\bar{a}^2}{2}\right) \sin 2(t + \bar{\theta}) - \frac{\bar{a}^2}{8} \sin 4(t + \bar{\theta}) \end{pmatrix} \quad (34)$$

$$u_1 = \begin{pmatrix} \frac{\bar{a}^3}{32} \sin 4(t + \bar{\theta}) - \frac{\bar{a}}{4} \sin 2(t + \bar{\theta}) \\ \frac{\bar{a}^2}{32} \cos 4(t + \bar{\theta}) - \frac{1}{4} \left(1 - \frac{\bar{a}^2}{2}\right) \cos 2(t + \bar{\theta}) \end{pmatrix}$$

$$a = \bar{a} + \varepsilon \left(\frac{\bar{a}^3}{32} \sin 4(t + \bar{\theta}) - \frac{\bar{a}}{4} \sin 2(t + \bar{\theta}) \right) \quad (37)$$

$$\theta = \bar{\theta} + \varepsilon \left(\frac{\bar{a}^2}{32} \cos 4(t + \bar{\theta}) - \frac{1}{4} \left(1 - \frac{\bar{a}^2}{2}\right) \cos 2(t + \bar{\theta}) \right)$$

Второе приближение:

$$x_2 = \xi + \varepsilon u_1(\xi, t) + \varepsilon^2 u_2(\xi, t) \quad (22)$$

$$\dot{\xi} = \varepsilon A_1(\xi) + \varepsilon^2 A_2(\xi) \quad (23)$$

$$F(\xi, t) = X_2(\xi, t) + \frac{\partial X_1}{\partial \xi} u_1(\xi, t) u_1(\xi, t) - A_1(\xi) \frac{\partial u_1}{\partial \xi}(\xi, t) \quad (25)$$

=0

$$A_2(\xi) = \bar{F}(\xi, t) \quad (26)$$

Поскольку выкладки становятся весьма громоздкими, ограничимся тем, что приведем получающиеся в результате уравнения:

$$\dot{\bar{a}} = \varepsilon \frac{\bar{a}}{2} \left(1 - \frac{\bar{a}^2}{4} \right)$$

$$\dot{\bar{\theta}} = -\varepsilon^2 \left(\frac{1}{8} - \frac{\bar{a}^2}{8} + \frac{7\bar{a}^4}{256} \right) \quad (36)$$

Стационарное решение:

$$\bar{a} = \frac{2y_0}{\sqrt{y_0^2 + (4 - y_0^2)e^{-\varepsilon t}}} \xrightarrow{t \rightarrow \infty} 2,$$

$$\dot{\bar{\theta}} \xrightarrow{t \rightarrow \infty} -\frac{\varepsilon^2}{16} \Rightarrow \bar{\theta} \xrightarrow{t \rightarrow \infty} -\frac{\varepsilon^2}{16} + \theta_0$$